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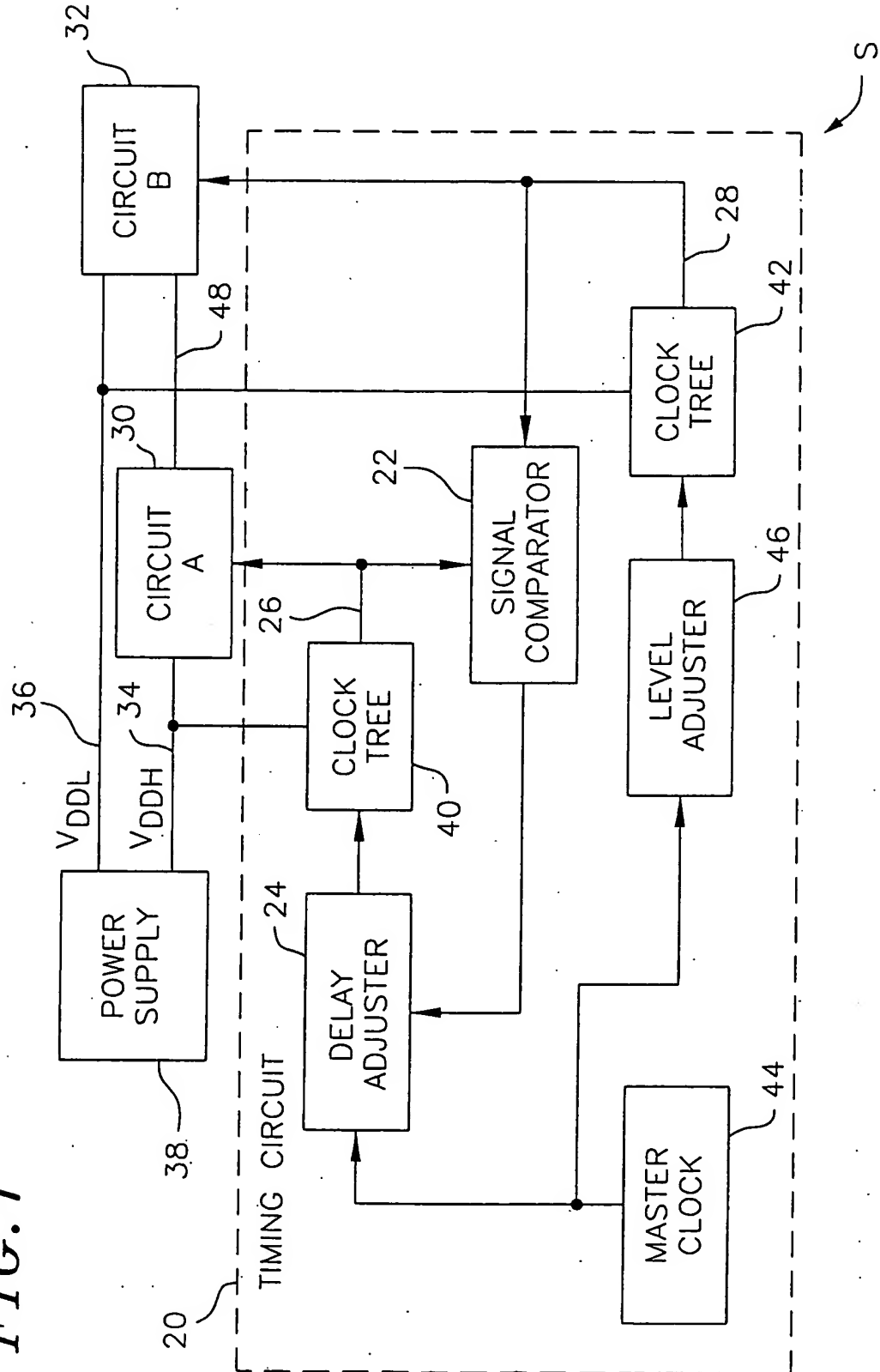
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FIG. 1



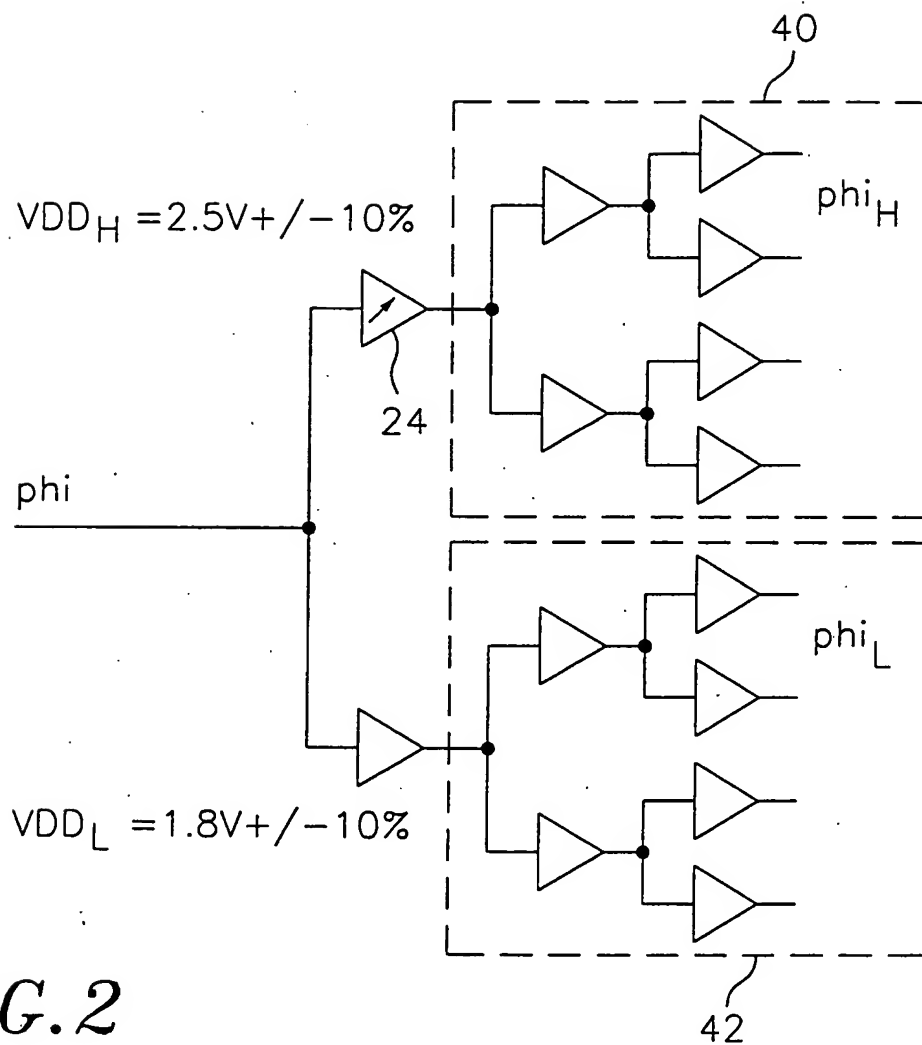


FIG. 2

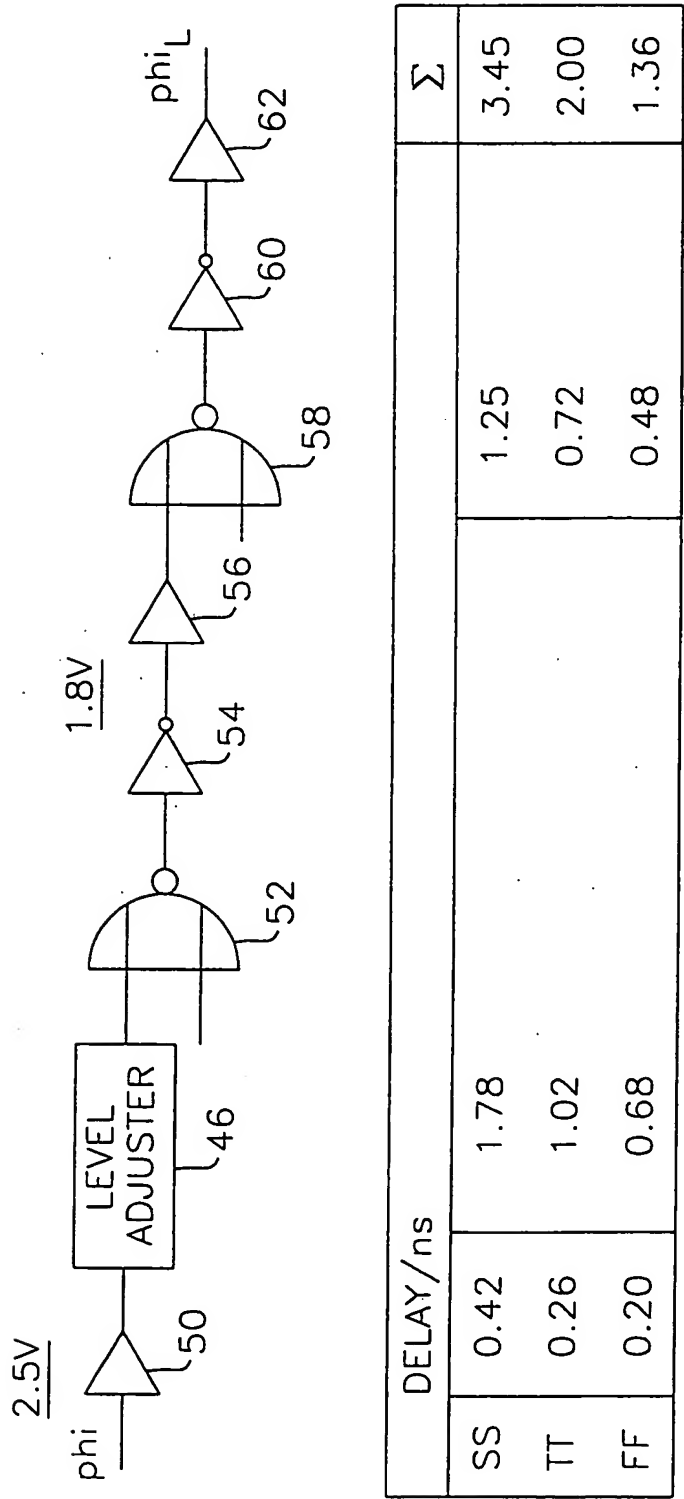


FIG.3

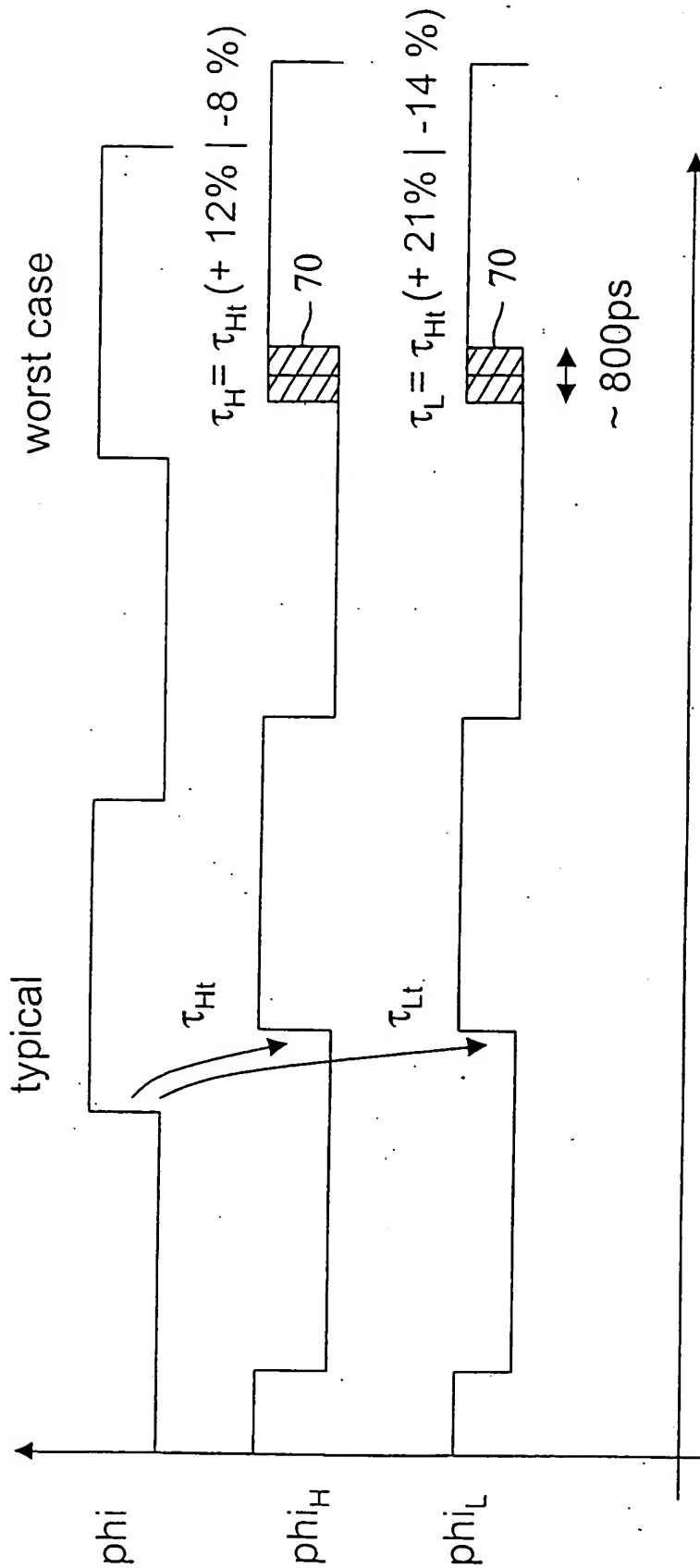


FIG. 4

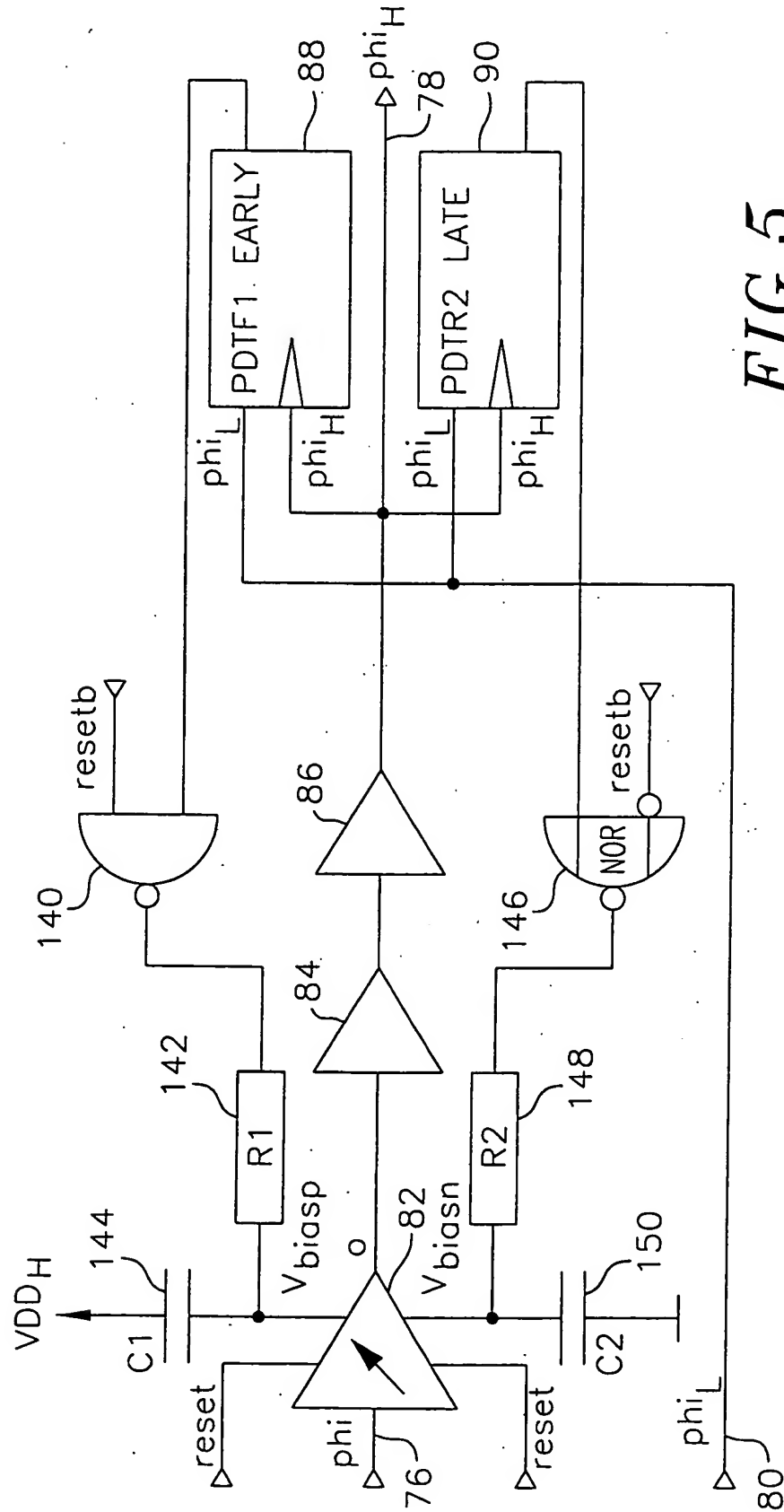
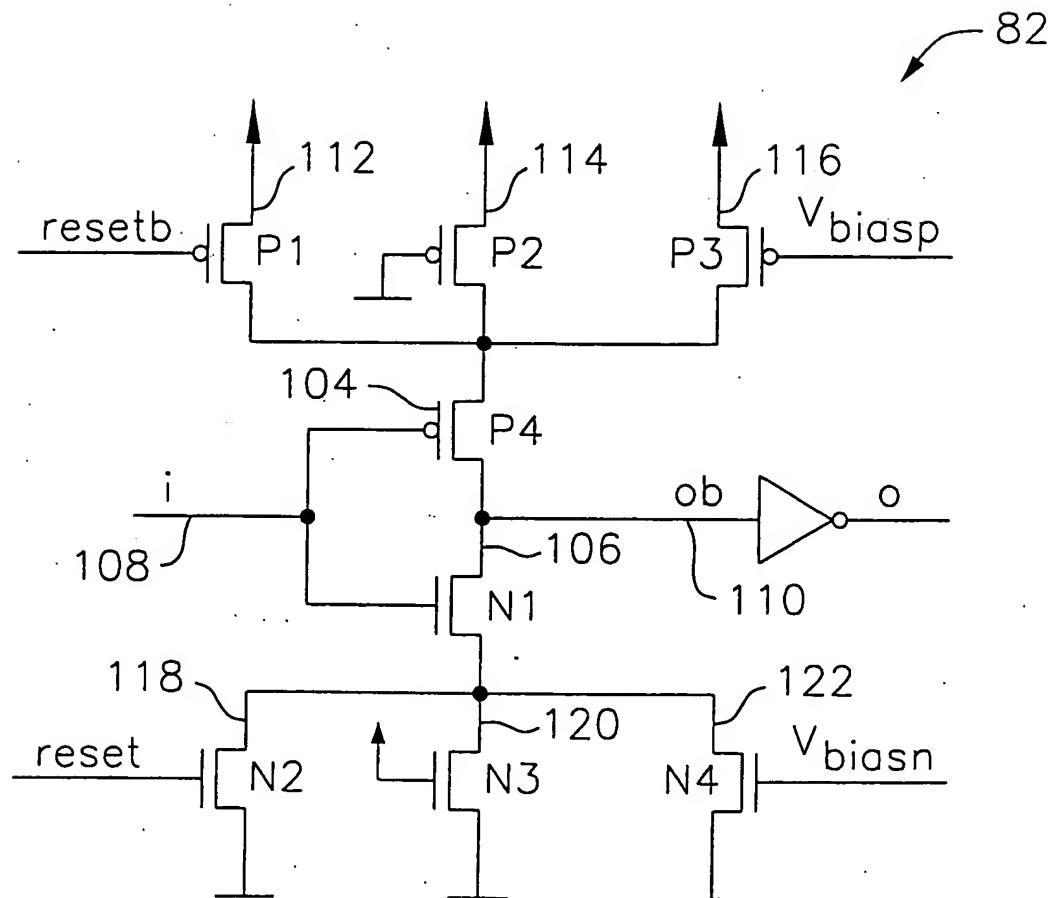


FIG. 5

FIG. 6



tr: rise time
 tf: fall time

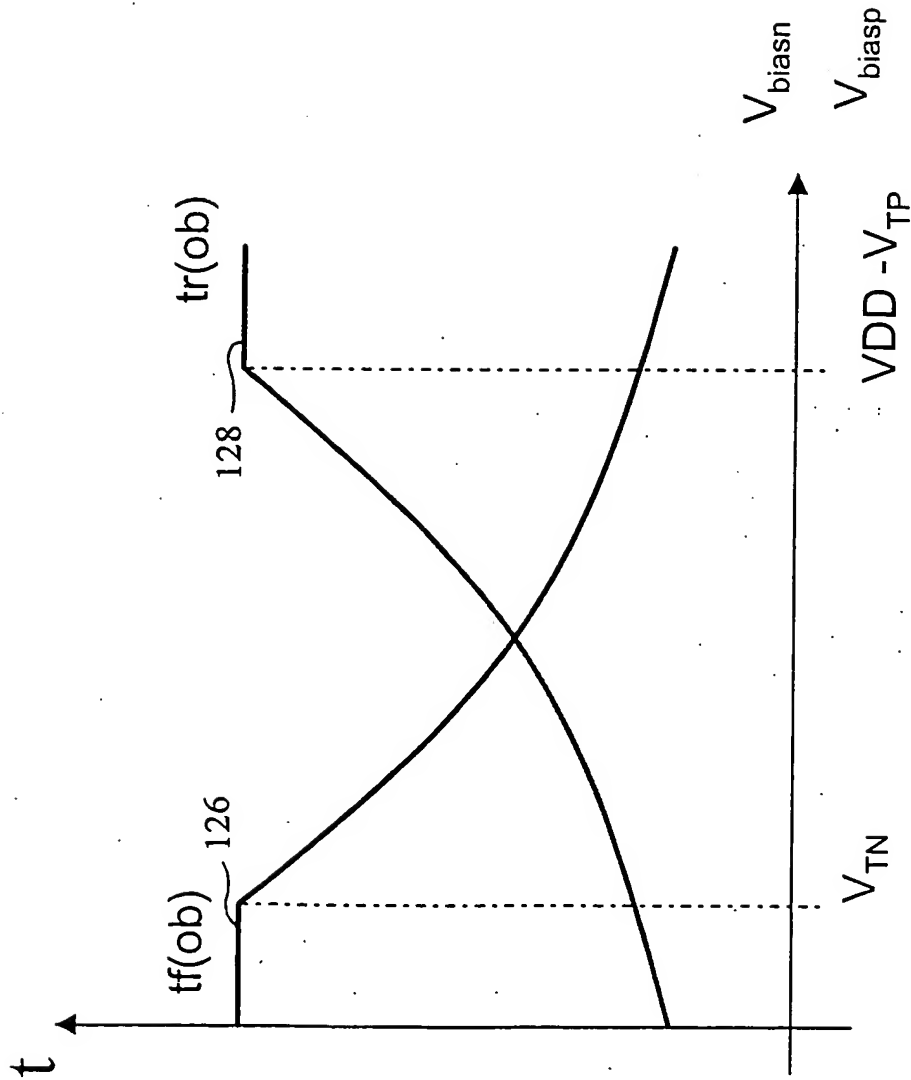


FIG. 7

FIG. 8A

delays, CORNER=2, 01phi>01phi1

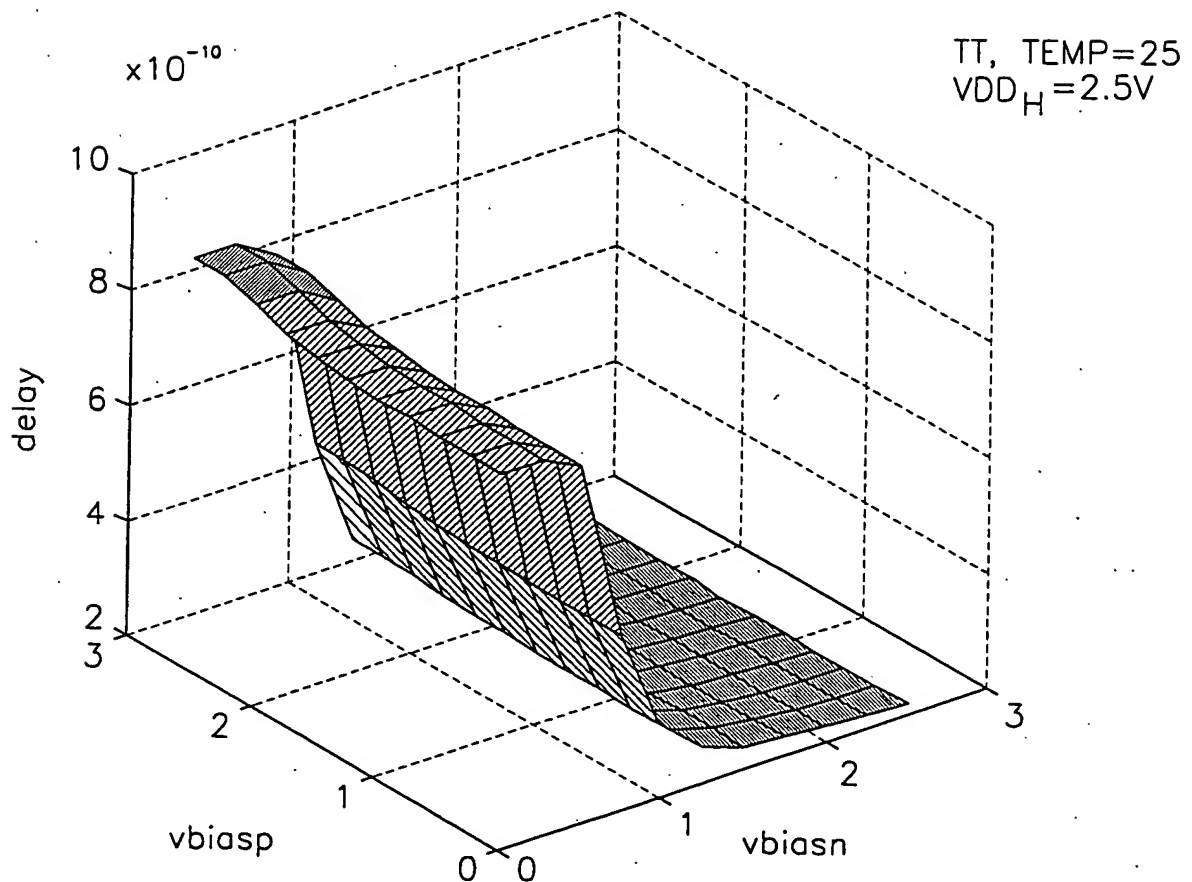


FIG. 8B

delays, CORNER=2, 01phi>01phi1

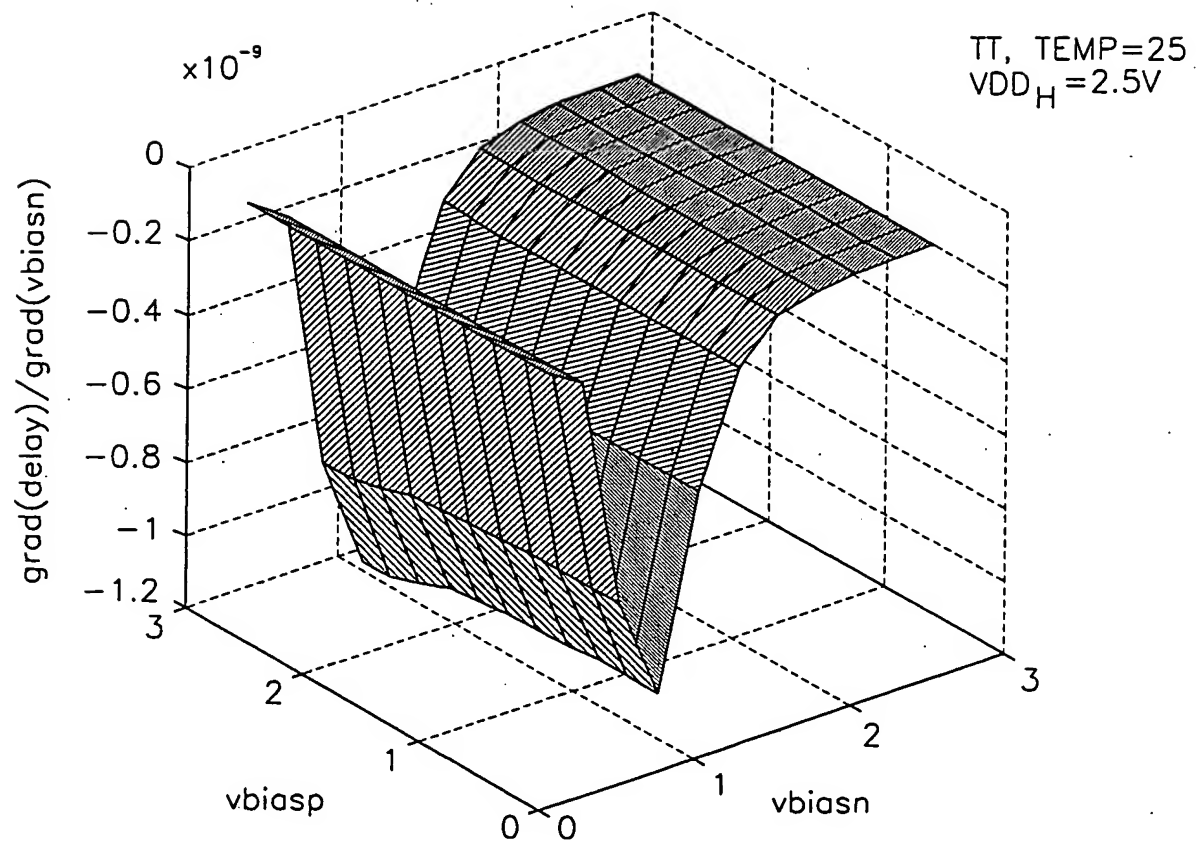


FIG. 8C

delays, CORNER=2, 10phi>10phi1

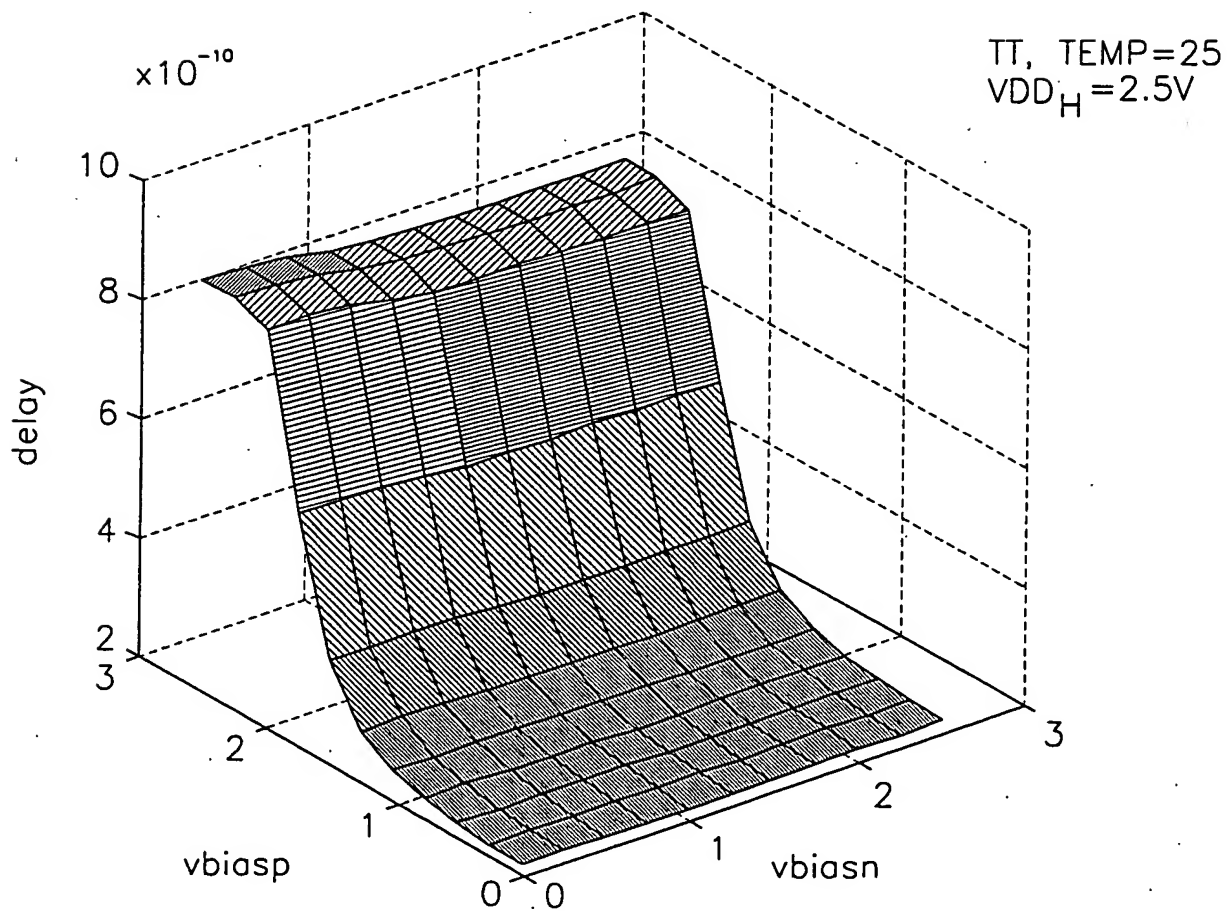


FIG. 8D

delays, CORNER=2, 10phi>10phi1

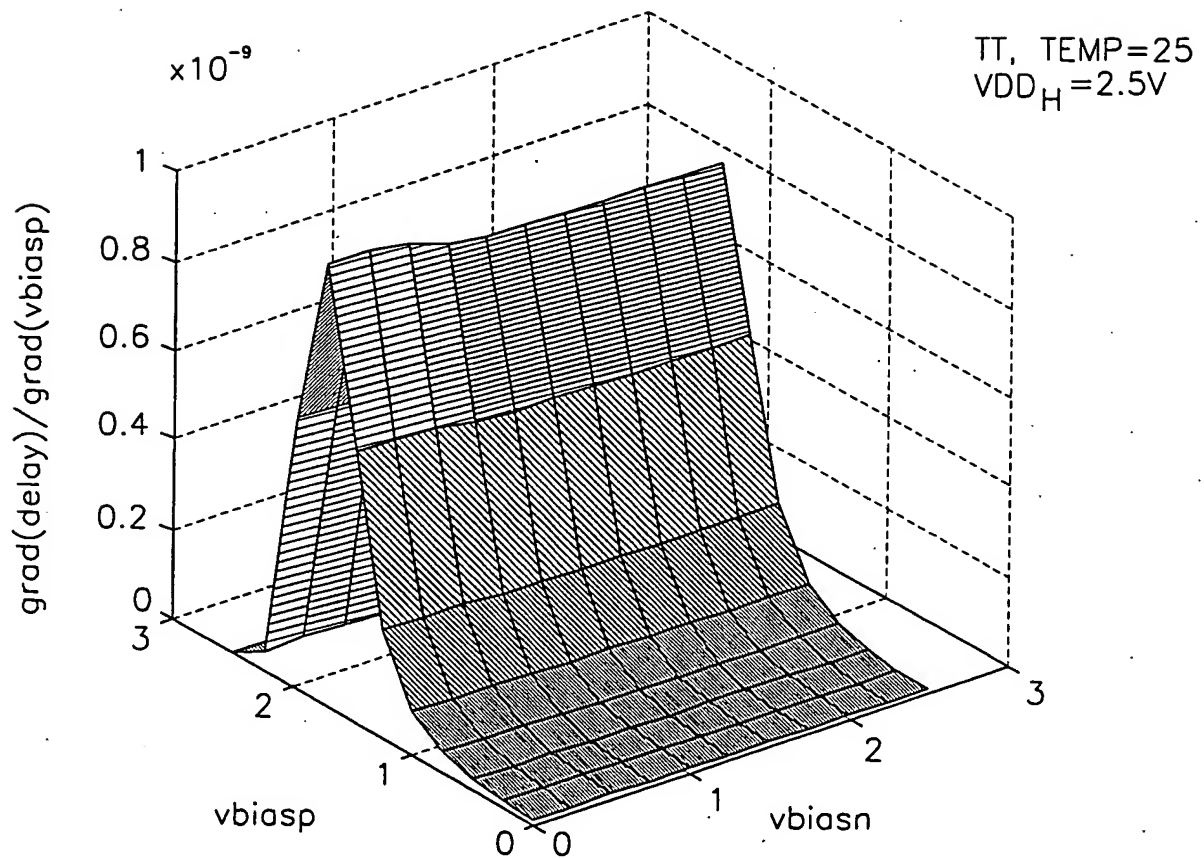


FIG. 9

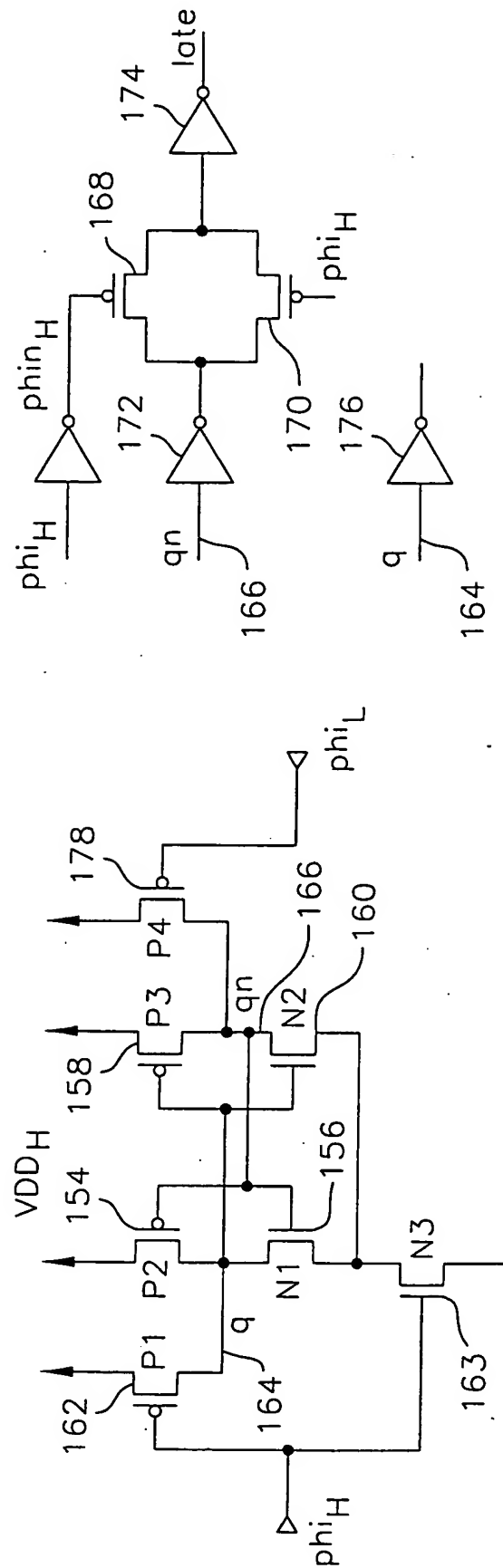
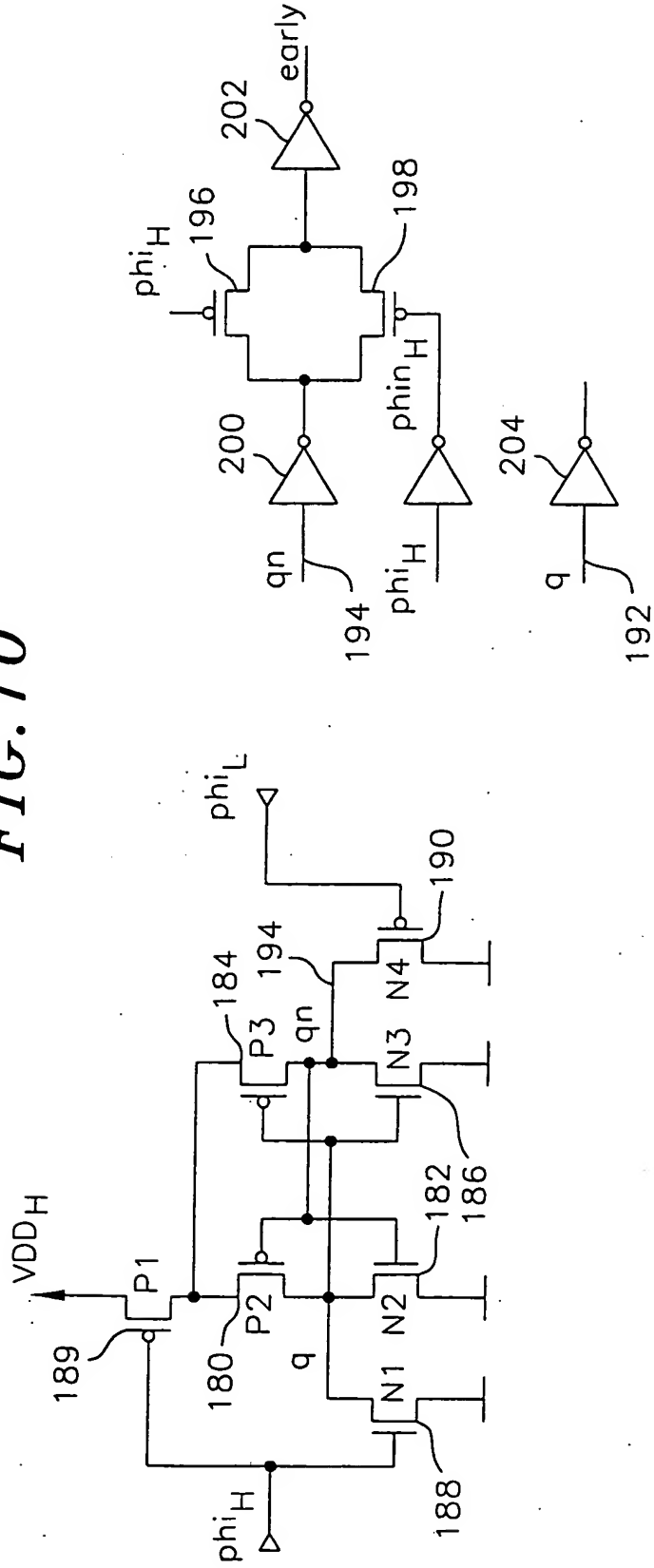
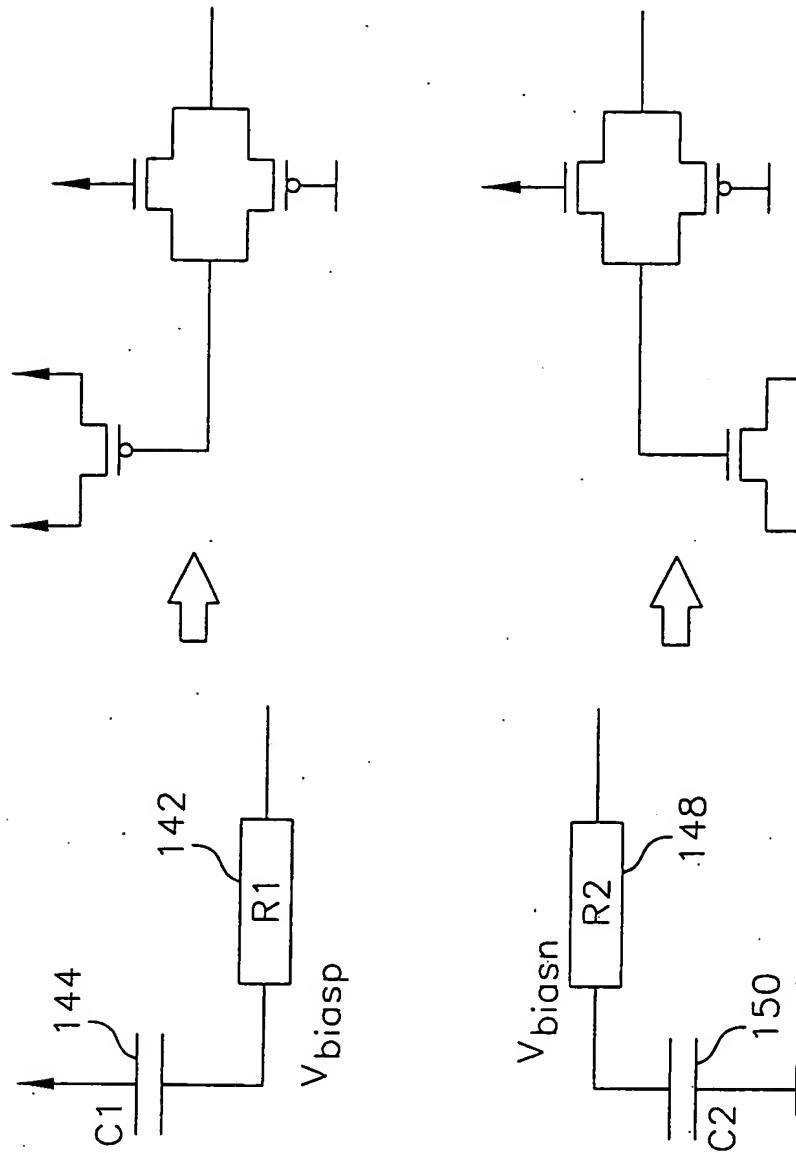


FIG. 10





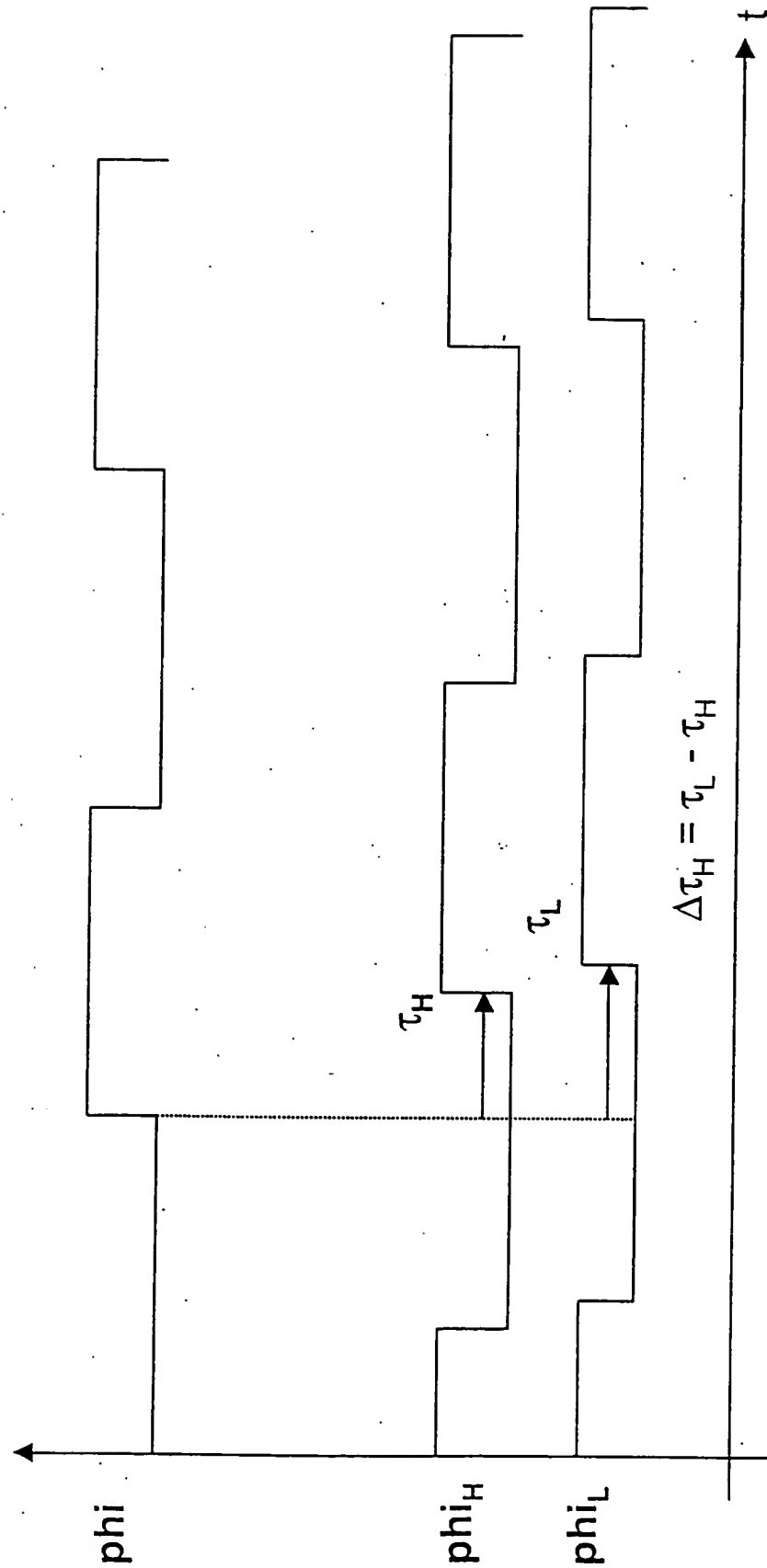


FIG. 12

FIG. 13A

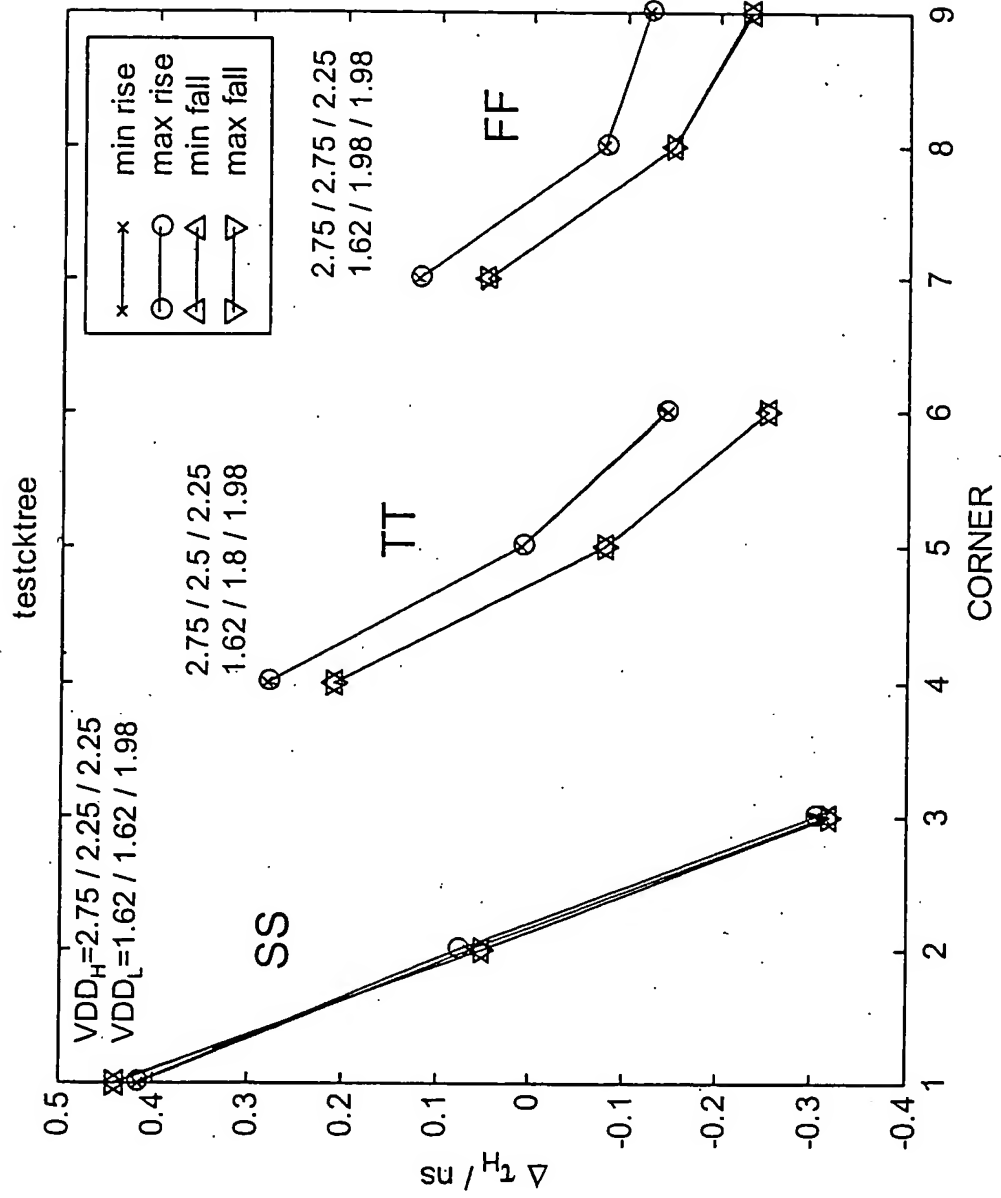


FIG. 13B

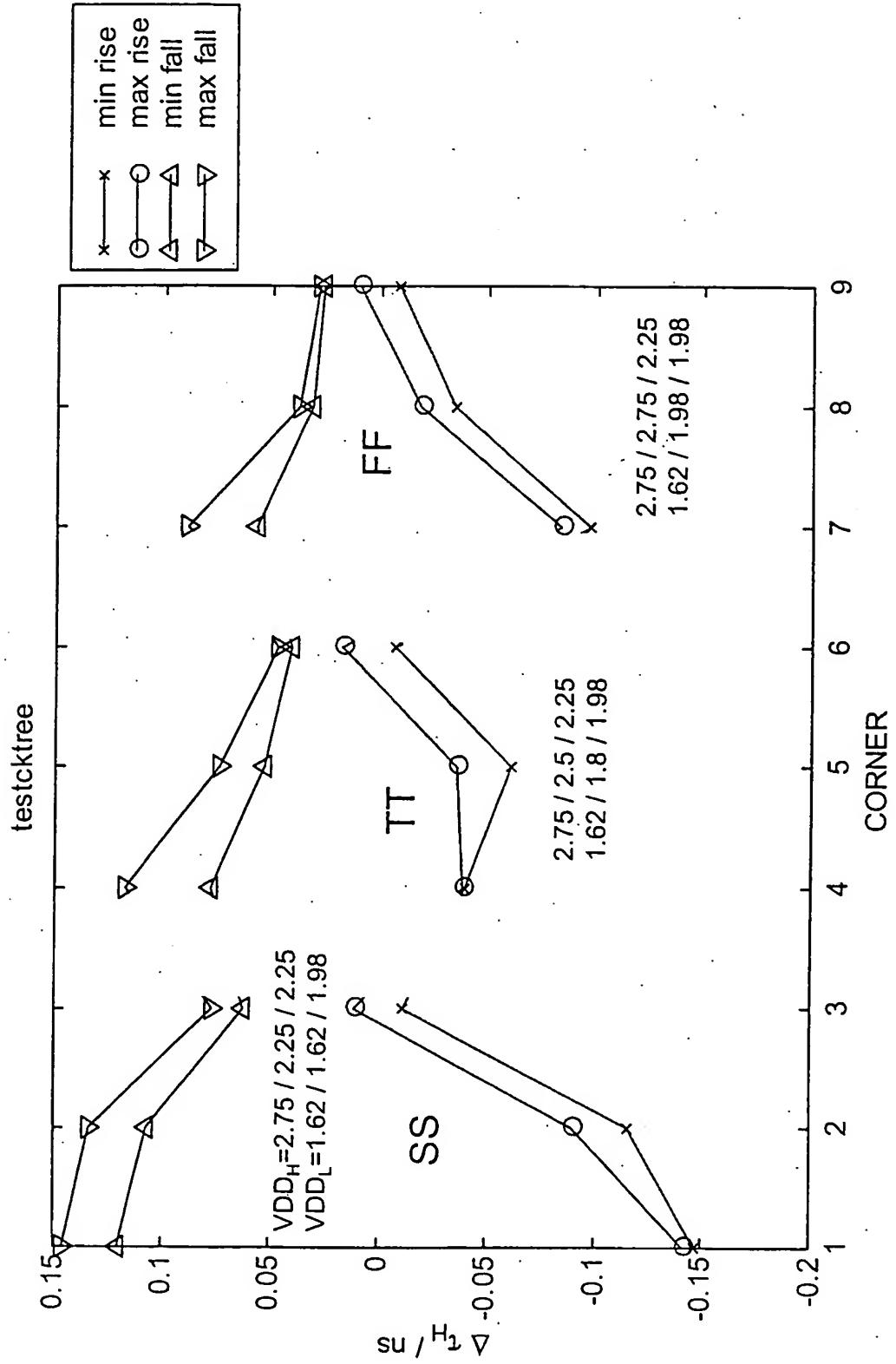


FIG. 13C

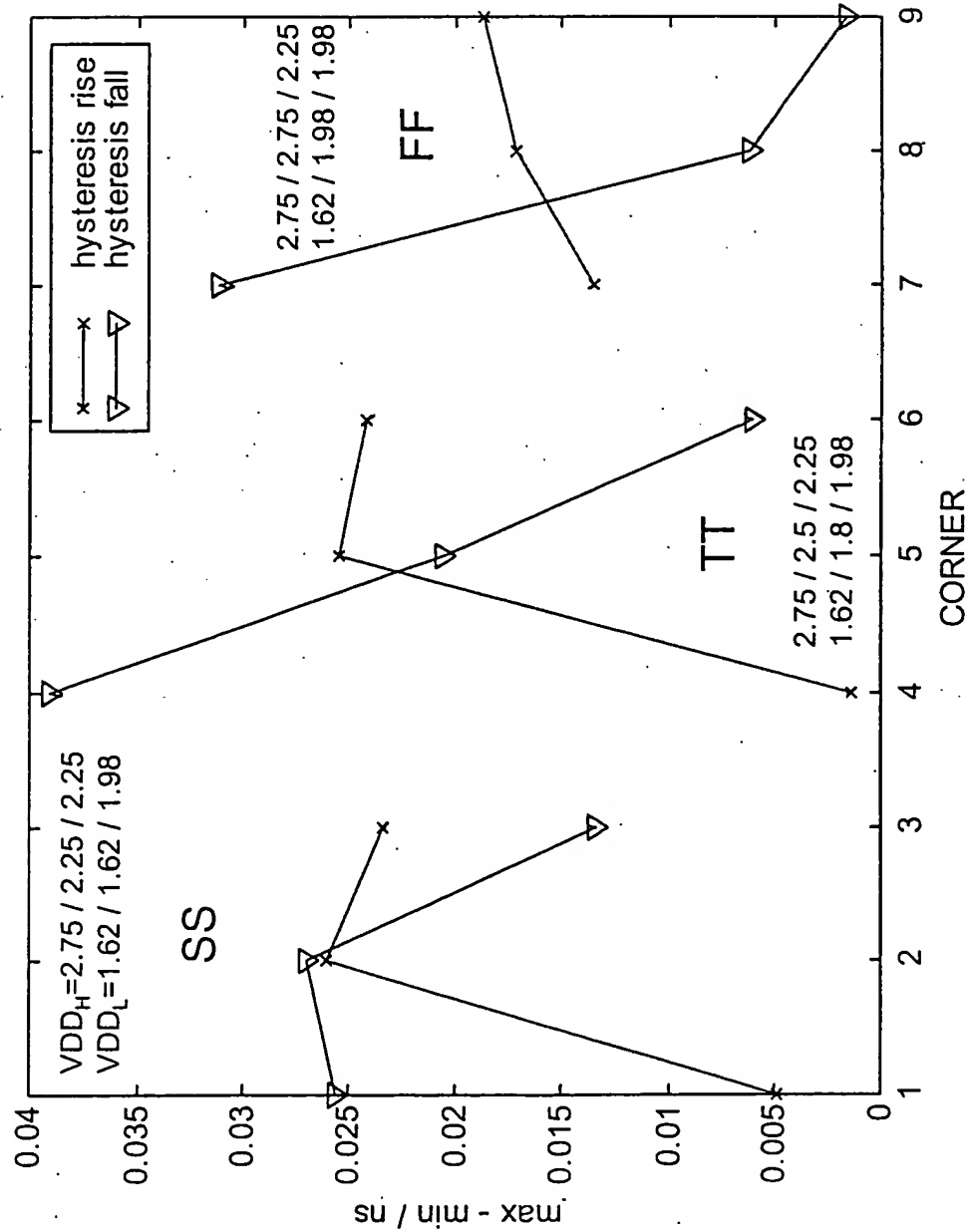


FIG. 13D

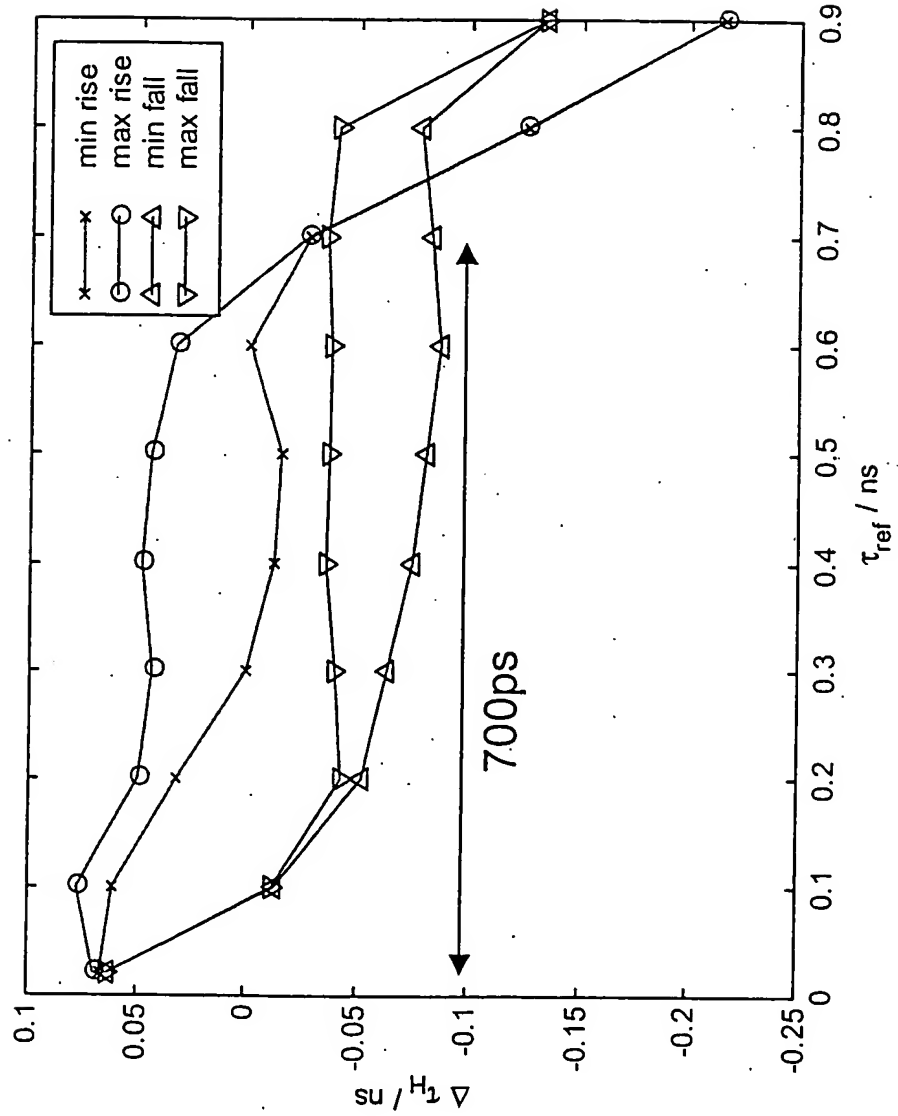
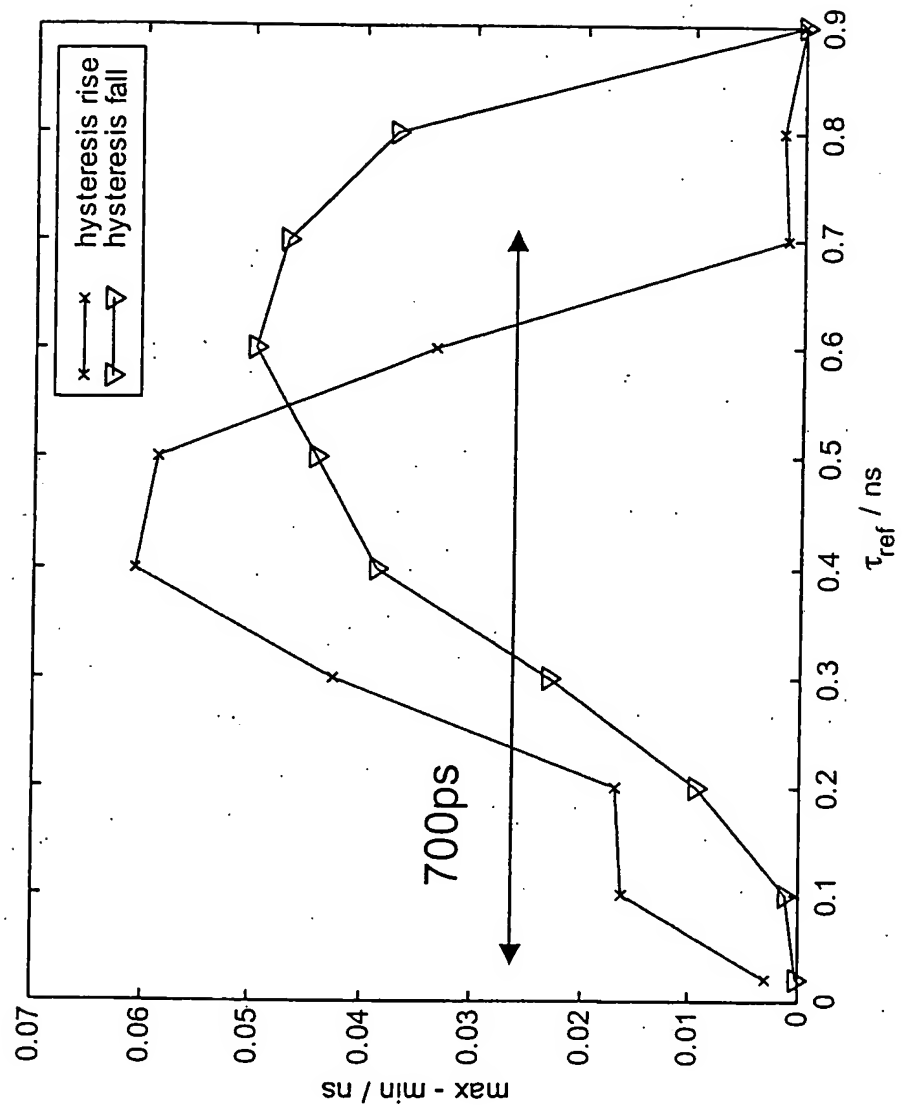


FIG. 13E



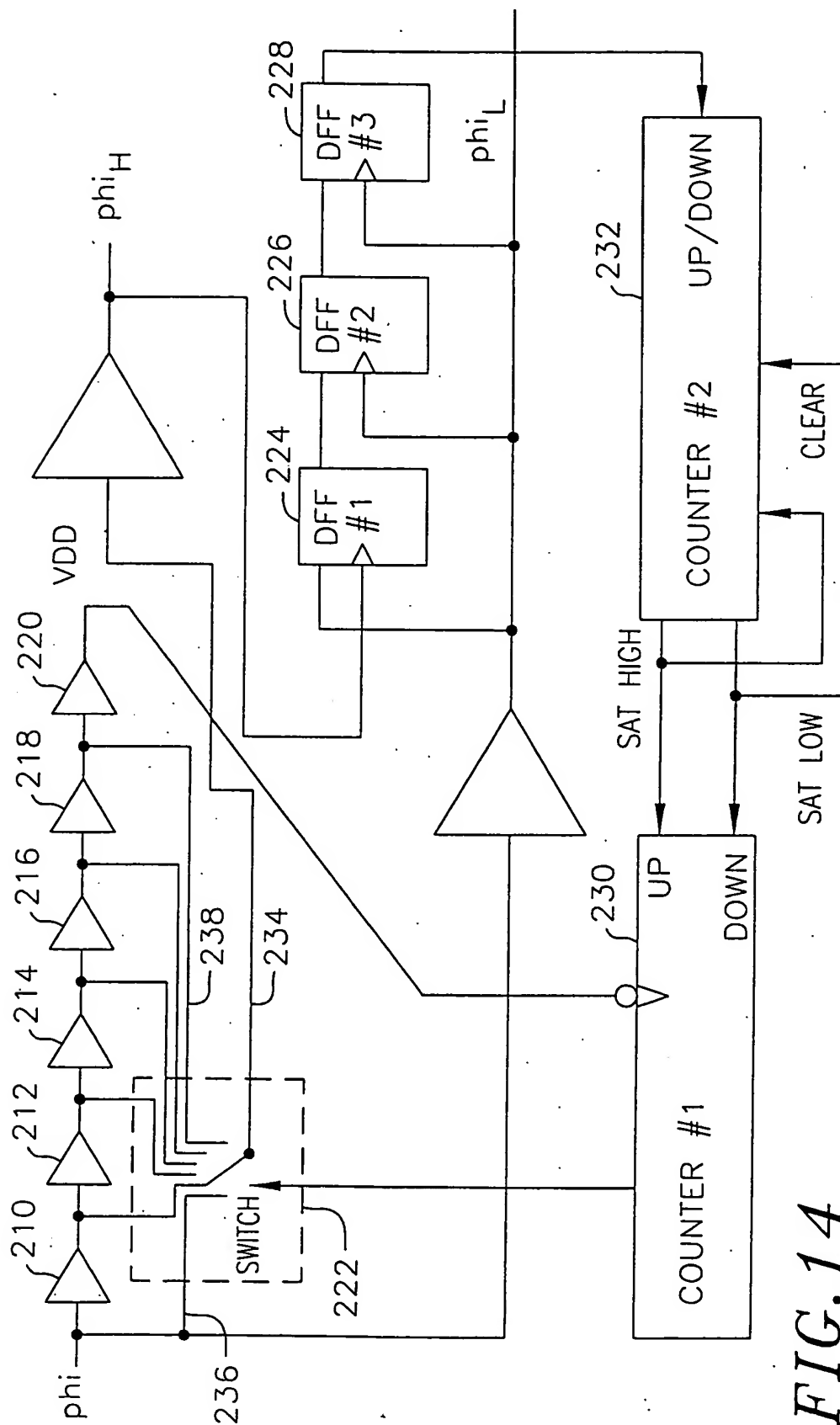


FIG. 15. SYSTEM AND METHOD FOR

FIG. 15

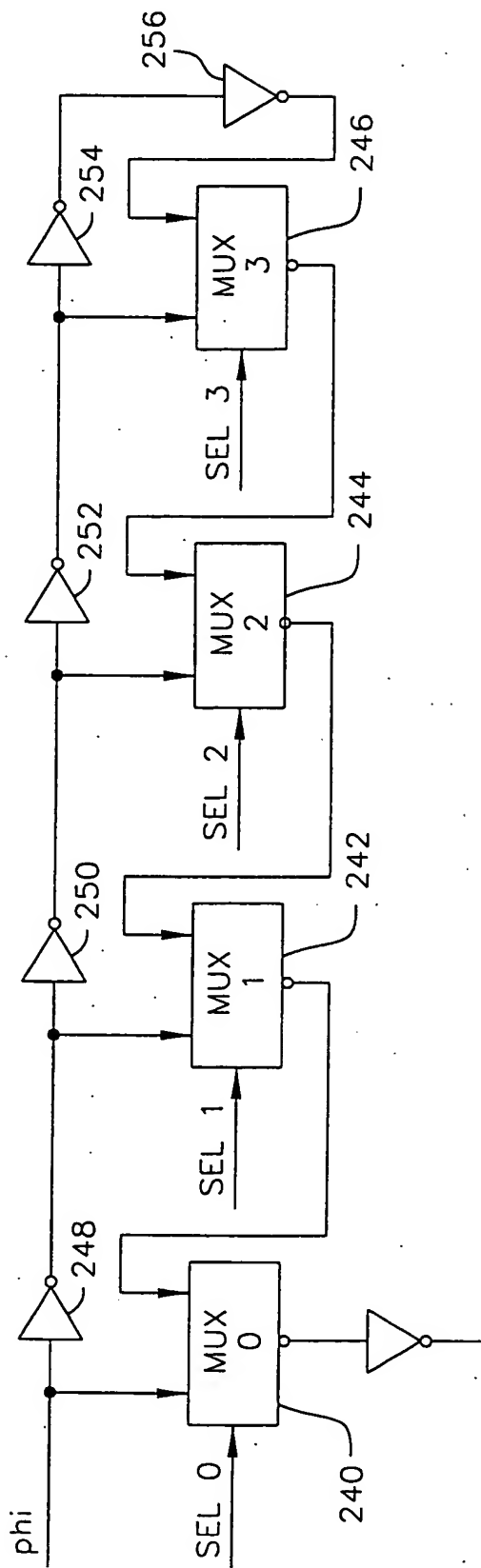


FIG. 16: SYSTEM AND METHOD FOR

FIG. 16

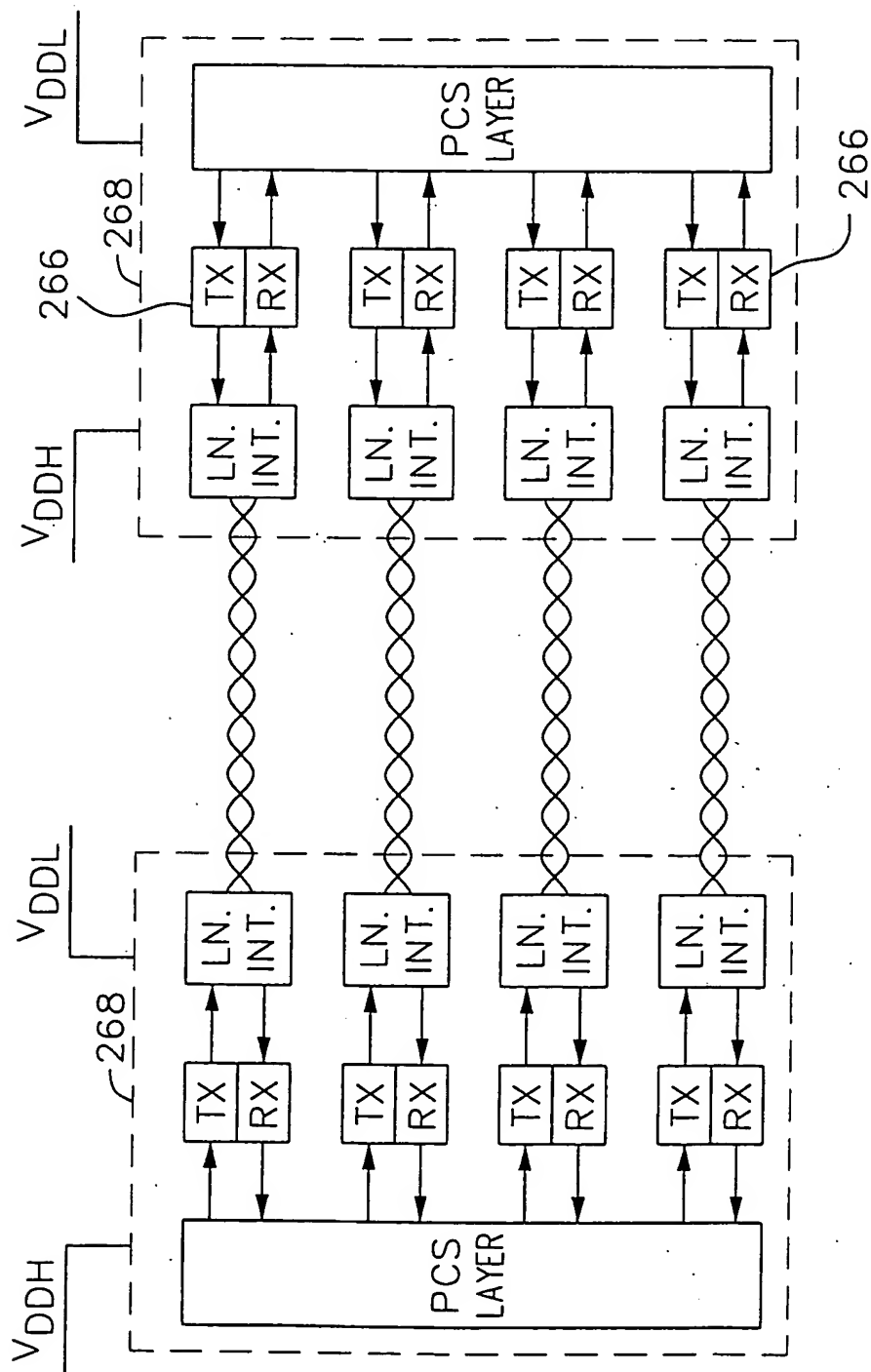


FIG. 17. SYSTEM AND METHOD FOR

FIG. 17

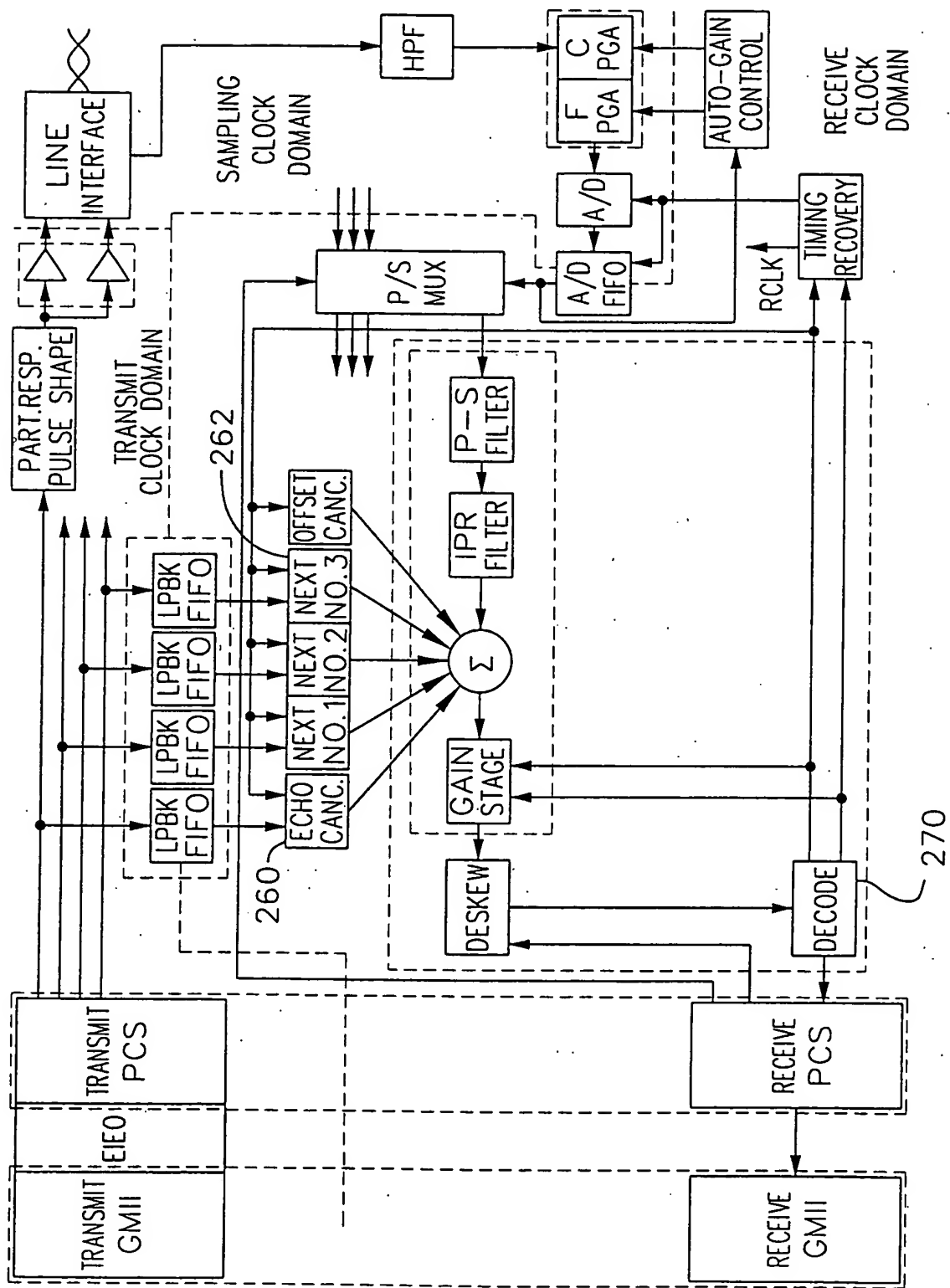


FIG. 18. SYSTEM AND METHOD FOR

FIG. 18

